# Building Finite-State Machines

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#### Xerox Finite-State Tool

- You'll use it for homework ...
- Commercial product (but we have academic license here)
  - One of several finite-state toolkits available
  - This one is easiest to use but doesn't have probabilities
- Usage
  - Enter a regular expression; it builds FSA or FST
  - Now type in input string
    - FSA: It tells you whether it's accepted
    - FST: It tells you all the output strings (if any)
    - Can also invert FST to let you map outputs to inputs
  - Could hook it up to other NLP tools that need finitestate processing of their input or output

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## Common Regular Expression Operators

concatenation EF E\*, E+ iteration union EIF intersection complementation, minus ~E, \x, E-F E .x. F crossproduct composition E .o. F ٠٥. upper (input) language E.u "domain" .u lower (output) language E.I "range"

### What the Operators Mean

- [blackboard discussion]
- [Composition is the most interesting case: see following slides.]

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#### How to define transducers?

- state set Q
- initial state i
- set of final states F
- input alphabet  $\Sigma$  (also define  $\Sigma^*$ ,  $\Sigma$ +,  $\Sigma$ ?)
- output alphabet ∆
- transition function d: Q x Σ? --> 2<sup>Q</sup>
- output function s: Q x Σ? x Q --> Δ\*

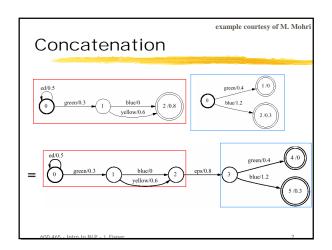
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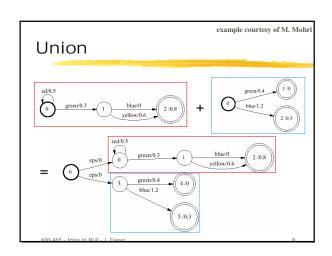
slide courtesy of L. Karttunen (modified)

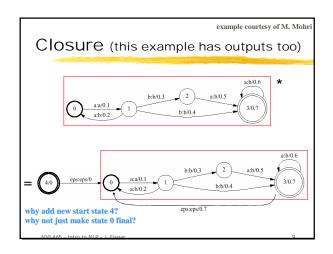
## How to implement?

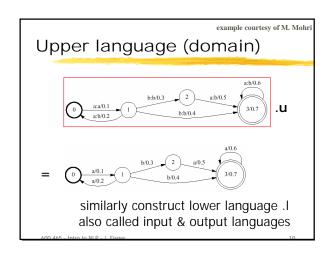
concatenation E\*, E+ iteration union E | F complementation, minus ~E, \x, E-F intersection E & F E .x. F crossproduct E .o. F composition .0. upper (input) language E.u "domain" .u lower (output) language E.I "range"

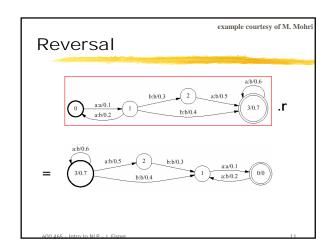
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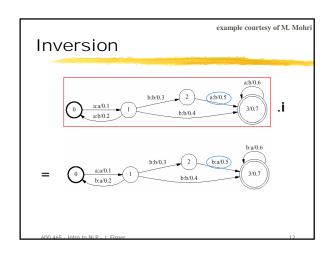








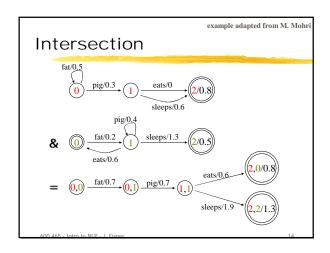


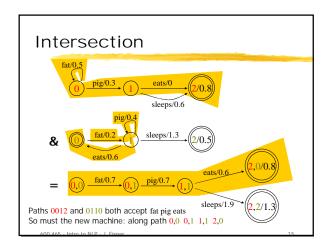


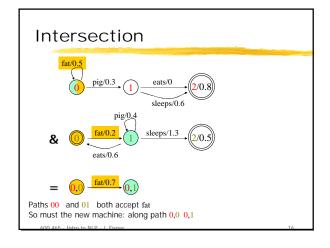
## Complementation

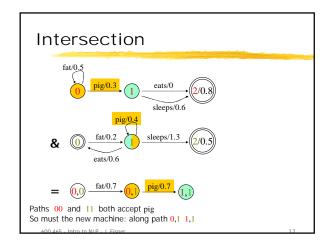
- Given a machine M, represent all strings not accepted by M
- Just change final states to non-final and vice-versa
- Works only if machine has been determinized and completed first (why?)

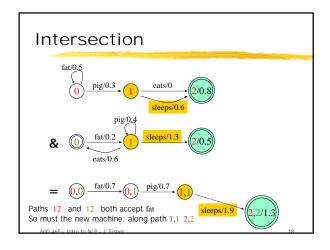
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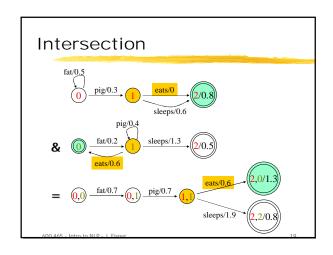


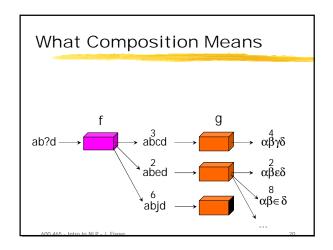


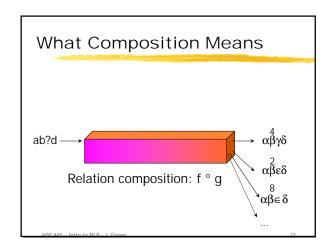


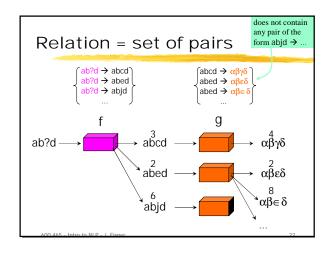


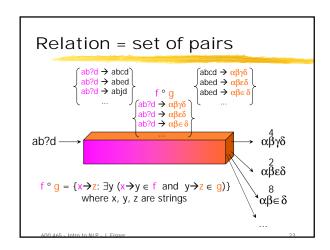


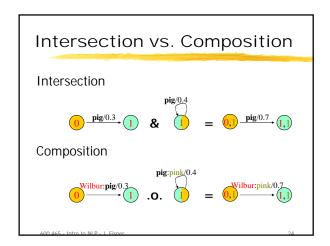


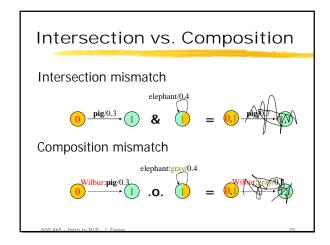


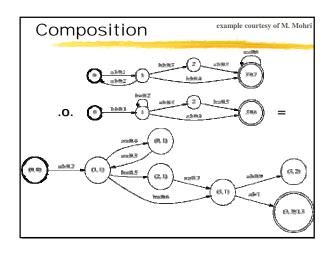


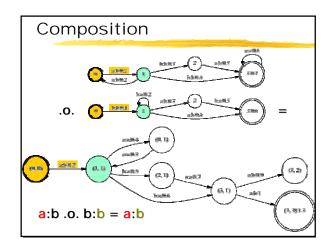


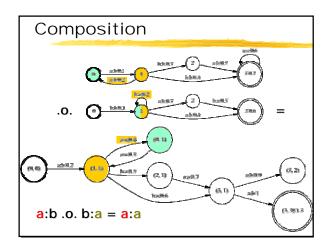


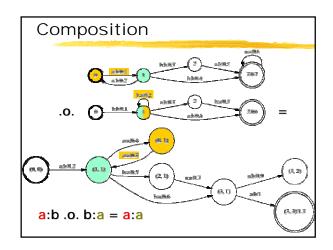


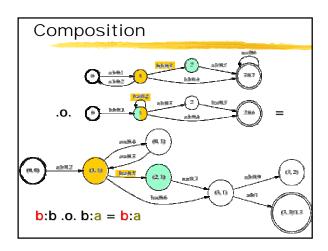


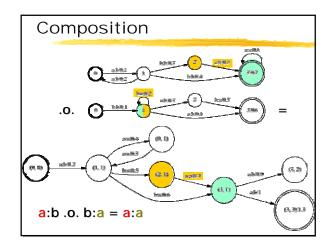


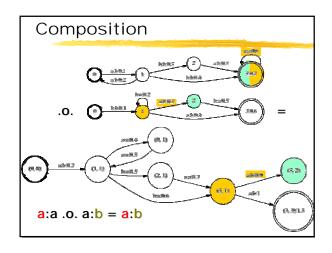


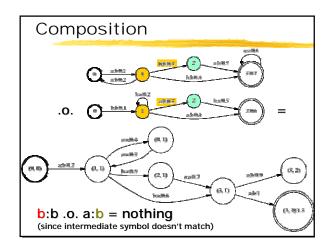


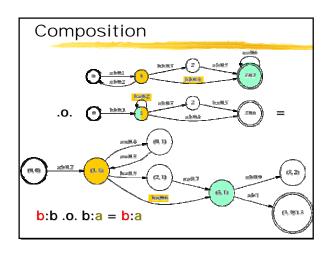


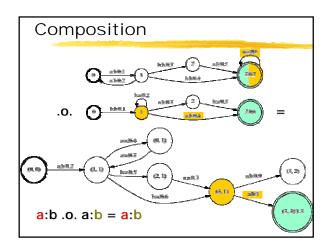


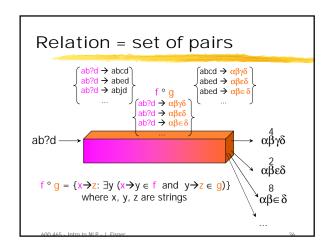












### Composition with Sets

- We've defined A .o. B where both are FSTs
- Now extend definition to allow one to be a FSA
- Two relations (FSTs):

```
A \circ B = \{x \rightarrow z : \exists y (x \rightarrow y \in A \text{ and } y \rightarrow z \in B)\}
```

Set and relation:

```
A \circ B = \{x \rightarrow z: x \in A \text{ and } x \rightarrow z \in B\}
```

Relation and set:

```
A \circ B = \{x \rightarrow z: x \rightarrow z \in A \text{ and } z \in B\}
```

Two sets (acceptors) – same as intersection:

 $A \circ B = \{x:$ 

 $x \in A$  and

 $x \in B$ 

## Composition and Coercion

- Really just treats a set as identity relation on set {abc, pqr, ...} = {abc→abc, pqr→pqr, ...}
- Two relations (FSTs):

```
A \circ B = \{x \rightarrow z : \exists y (x \rightarrow y \in A \text{ and } y \rightarrow z \in B)\}
```

• Set and relation is now special case (if  $\exists y \text{ then } y=x$ ):

$$A \circ B = \{x \rightarrow z: x \rightarrow x \in A \text{ and } x \rightarrow z \in B\}$$

- Relation and set is now special case (if ∃y then y=z):
- $A \circ B = \{x \rightarrow z: x \rightarrow z \in A \text{ and } z \rightarrow z \in B \}$
- Two sets (acceptors) is now special case:

 $A \circ B = \{x \rightarrow z: x \rightarrow x \in A \text{ and } x \rightarrow x \in B \}$ 

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## 3 Uses of Set Composition:

- Feed string into Greek transducer:
  - {abed  $\rightarrow$  abed} .0. Greek = {abed  $\rightarrow$  αβεδ, abed  $\rightarrow$  αβεδ}
  - {abed} .o. Greek = {abed  $\rightarrow \alpha\beta\epsilon\delta$ , abed  $\rightarrow \alpha\beta\epsilon\delta$ }
  - [{abed} .o. Greek]. $I = {\alpha\beta\epsilon\delta, \alpha\beta\epsilon\delta}$
- Feed several strings in parallel:
  - {abcd, abed} .o. Greek
  - $= \{abcd \rightarrow \alpha\beta\gamma\delta, abed \rightarrow \alpha\beta\epsilon\delta, abed \rightarrow \alpha\beta\epsilon\delta\}$
  - [{abcd,abed} .o. Greek].I = {αβγδ, αβεδ, αβ∈δ}
- Filter result via Noε = {αβγδ, αβ∈δ, ...}
  - {abcd,abed} .o. Greek .o. No $\varepsilon$ = {abcd $\rightarrow \alpha\beta\gamma\delta$ , abed $\rightarrow \alpha\beta\in\delta$ }
  - (abca y up lo, abca y upe o

# What are the "basic" transducers?

- The operations on the previous slides combine transducers into bigger ones
- But where do we start?
- a: $\epsilon$  for  $a \in \Sigma$
- <u>a:ε</u> (Ω)
- $\varepsilon$ : x for  $x \in \Delta$
- $\underbrace{\phantom{a}}_{\epsilon:x}$
- Q: Do we also need a:x? How about ε:ε?

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40